

Preparing Raspberry Pi

Install Raspbian Jessie on the Raspberry Pi

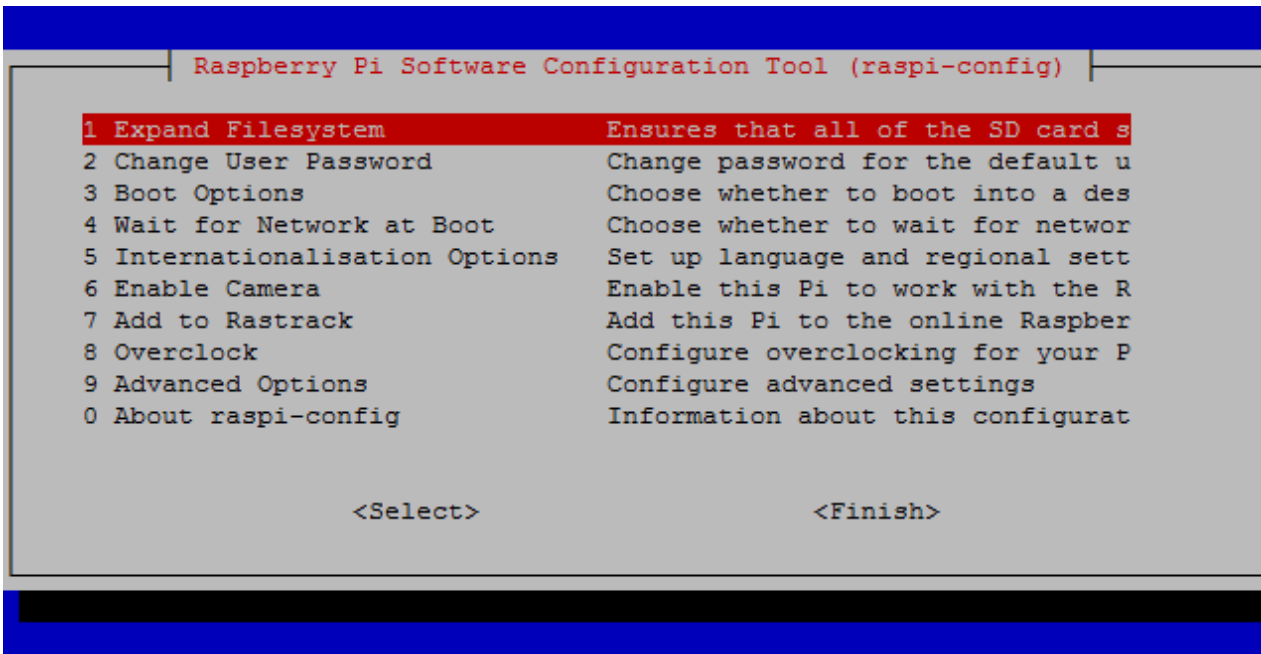
Click [HERE](#) to download Raspbian Jessie.

Expand file system

Run the following command line within the Raspberry Pi's terminal.

```
sudo raspi-config
```

You should see a blue screen with options in a gray box in the center, like so



```
Raspberry Pi Software Configuration Tool (raspi-config)

1 Expand Filesystem          Ensures that all of the SD card s
2 Change User Password      Change password for the default u
3 Boot Options              Choose whether to boot into a des
4 Wait for Network at Boot  Choose whether to wait for networ
5 Internationalisation Options Set up language and regional sett
6 Enable Camera             Enable this Pi to work with the R
7 Add to Rastrack           Add this Pi to the online Raspber
8 Overclock                 Configure overclocking for your P
9 Advanced Options         Configure advanced settings
0 About raspi-config        Information about this configurat

<Select>                    <Finish>
```

Choose "Expand Filesystem"

Choosing this option will expand your installation to fill the rest of the SD card, giving you more space to use for files. **You will need to reboot the Raspberry Pi to make this available.**

Update and Upgrade Packages

First, you will need to update your system's package list by entering the following command in terminal.

```
sudo apt-get update
```

Next, upgrade your installed packages to their latest versions with the command.

```
sudo apt-get upgrade
```

Running the upgrade may take up to 30 minutes depending on which version of the Raspberry Pi you have.

Download the sample code

To download the Atlas Scientific™ sample code, run the following commands within the Raspberry Pi's terminal.

```
cd ~
```

```
git clone https://github.com/AtlasScientific/Raspberry-Pi-sample-code.git
```

Once the sample code has finished downloading, you will be almost ready to begin using the Atlas Scientific™ EZO™ class circuits with your updated Raspberry Pi.

There are three different ways to interact with the Atlas Scientific™ EZO™ class circuits with your Raspberry Pi.

- **USB Mode**
- **I²C Mode**
- **UART Mode**

Sample code compatibility chart

	Pi 2	Pi 3	Pi Zero
USB (FTDI)	Compatible	Compatible	Compatible
I2C	Compatible	Compatible	Compatible
UART	Compatible	Incompatible	Compatible

The Raspberry Pi Foundation has failed to make a working UART on the Pi 3. Because of this no UART connected devices can run on a Raspberry Pi 3.

USB Mode



USB Mode

USB mode will let you communicate through the Raspberry Pi's USB port to any FTDI based USB device. This includes all USB based Atlas Scientific™ devices.

First, we need to install the libftdi package.

```
sudo apt-get install libftdi-dev
```

Next, we need to install the pylibftdi python package.

```
sudo pip install pylibftdi
```

We need to create a udev rule file by entering the following command in terminal.

```
sudo nano /etc/udev/rules.d/99-libftdi.rules
```

```
GNU nano 2.2.6 File: /etc/udev/rules.d/99-libftdi.rules
SUBSYSTEMS=="usb", ATTRS{idVendor}=="0403", ATTRS{idProduct}=="6015",
GROUP="dialout", MODE="0660", SYMLINK+="FTDISErial_Converter_${attr{serial}}
[ Read 2 lines ]
^G Get Help ^O WriteOut ^R Read File ^Y Prev Page ^K Cut Text ^C Cur Pos
^X Exit ^J Justify ^W Where Is ^V Next Page ^U UnCut Text ^T To Spell
```

Replace the current rule with following revised rule below.

```
SUBSYSTEMS=="usb", ATTRS{idVendor}=="0403", ATTRS{idProduct}=="6015",
GROUP="dialout", MODE="0660", SYMLINK+="FTDISErial_Converter_${attr{serial}}"
```

Press "CTRL+X", then "Y" and hit Enter to save & exit.

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Once the updated udev rule has been saved, a restart is required in order to apply changes to the rule.

```
sudo service udev restart
```

Lastly, we need to modify the FTDI python driver.

Since Atlas Scientific™ FTDI devices use *USB PID (0x6015)*, we need to tweak the original FTDI driver, by entering the following command in terminal.

```
sudo nano /usr/local/lib/python2.7/dist-packages/pylibftdi/driver.py
```

Move down to the line 70 and add **0x6015** at the end of line.

```
GNU nano 2.2.6 File: ...python2.7/dist-packages/pylibftdi/driver.py
FLUSH_OUTPUT = 3
# Device Modes
BITMODE_RESET = 0x00
BITMODE_BITBANG = 0x01

# Opening / searching for a device uses this list of IDs to search
# by default. These can be extended directly after import if required.
FTDI_VENDOR_ID = 0x0403
USB_VID_LIST = [FTDI_VENDOR_ID]
USB_PID_LIST = [0x6001, 0x6010, 0x6011, 0x6014] ← line 70

FTDI_ERROR_DEVICE_NOT_FOUND = -3

class Driver(object):
    """
    This is where it all happens...
    We load the libftdi library, and use it.
    """
    ...
^G Get Help  ^O WriteOut  ^R Read File  ^Y Prev Page  ^K Cut Text   ^C Cur Pos
^X Exit      ^J Justify   ^W Where Is  ^V Next Page  ^U UnCut Text ^T To Spell
```

Original line

```
USB_PID_LIST = [0x6001, 0x6010, 0x6011, 0x6014]
```

Modified line

```
USB_PID_LIST = [0x6001, 0x6010, 0x6011, 0x6014, 0x6015]
```

Press "CTRL+X", then "Y" and hit Enter to save & exit.

Your Atlas Scientific™ EZO™ class circuits are almost ready to work with your Raspberry Pi, we just have to run a simple test first.

Connect your FTDI based USB device and run the following command in the terminal.

```
sudo python -m pylibftdi.examples.list_devices
```

The program will report information about each connected device. You will get result like this:

```
FTDI:FT230X Basic UART:DA00TN6Q
```

Each FTDI adaptor has its own unique serial number.

In the result above, serial number is **DA00TN6Q**

Using pylibftdi module for Atlas Scientific™ EZO™ class circuits

Run the following commands in terminal.

```
cd ~/Raspberry-Pi-sample-code
```

```
sudo python ftdi.py
```

The program will present a list of available FTDI devies. Enter the index of the device you wish to use, and you will now be able to control an Atlas Scientific™ EZO™ class circuit via the USB port.

```
Discovered FTDI serial numbers:
Index: 0  Serial:  DA000IQH
Index: 1  Serial:  DA000JSH
=====
Please select a device index:
```

For more details on the commands and responses, please refer to the datasheets of each Atlas Scientific™ EZO™ class circuit in use.

I²C Mode



I²C Mode

Before we can start using the Atlas Scientific™ EZO™ class circuits with your Raspberry Pi, we have to install and enable I²C bus on the Raspberry Pi.

Run the following commands in terminal.

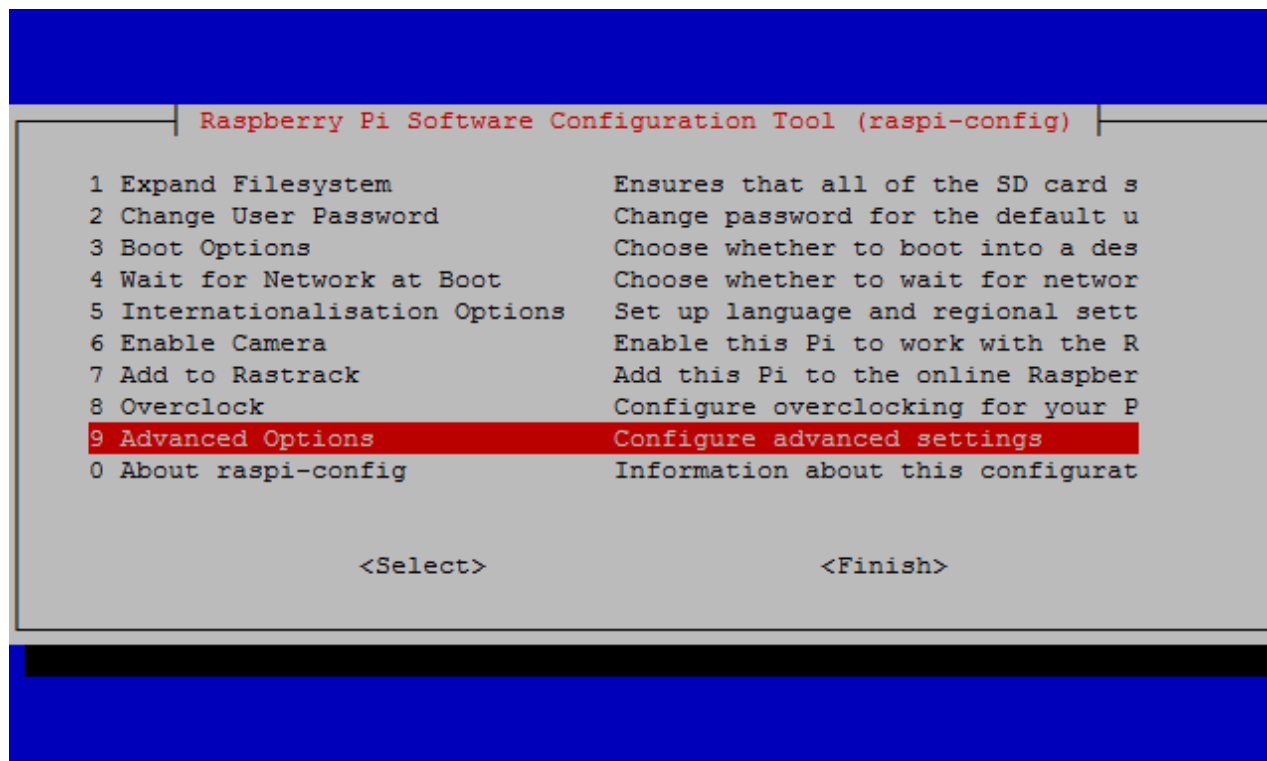
```
sudo apt-get install python-smbus
```

```
sudo apt-get install i2c-tools
```

Once those have finished installing, we need to head back to the Raspberry Pi config.

```
sudo raspi-config
```

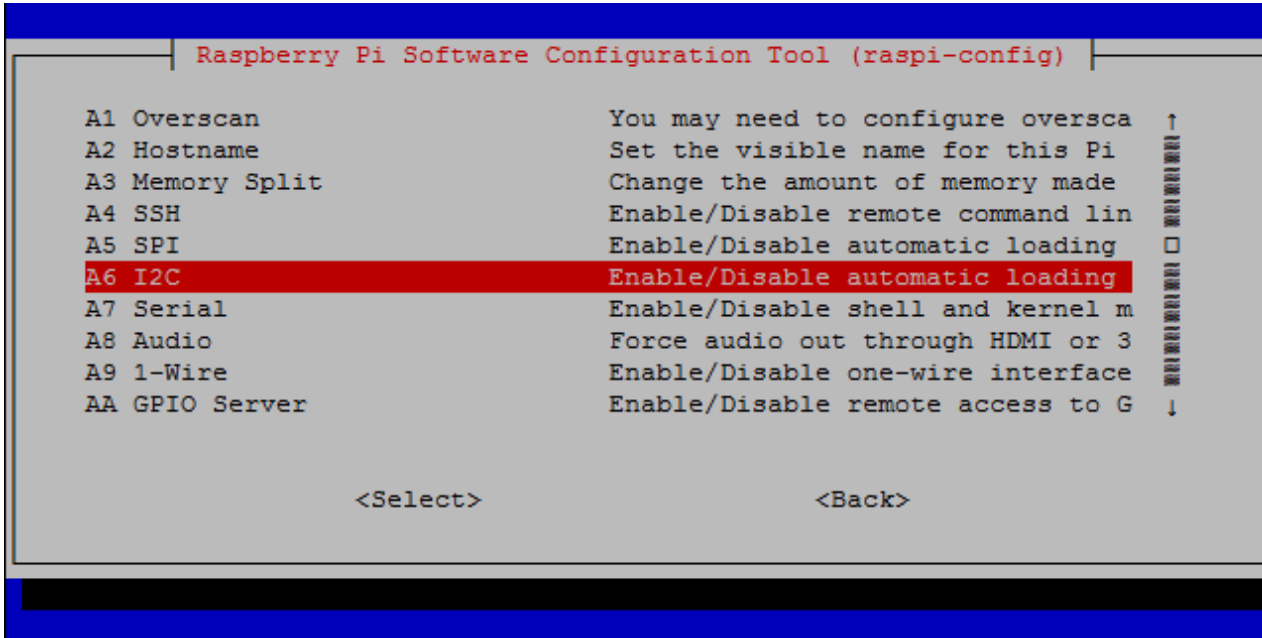
You should see a blue screen with options in a grey box in the center, like so



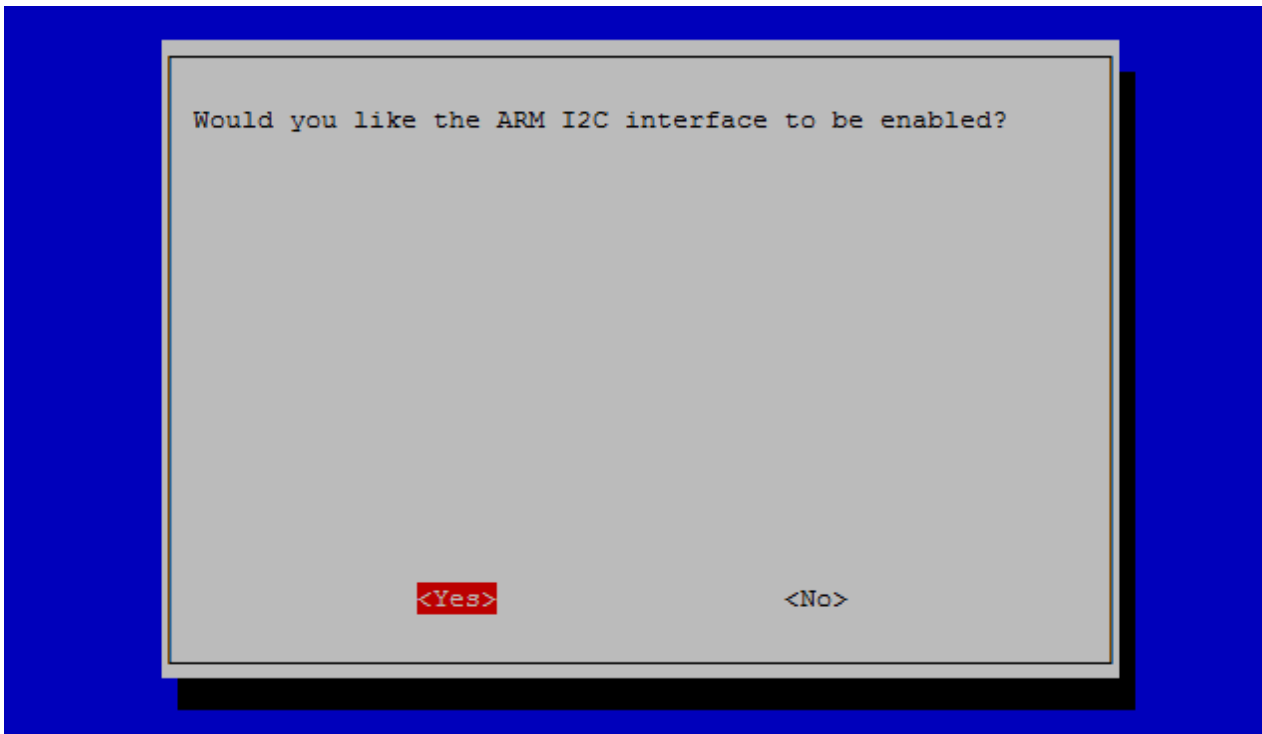
Choose "Advanced Options"

Raspberry Pi sample code

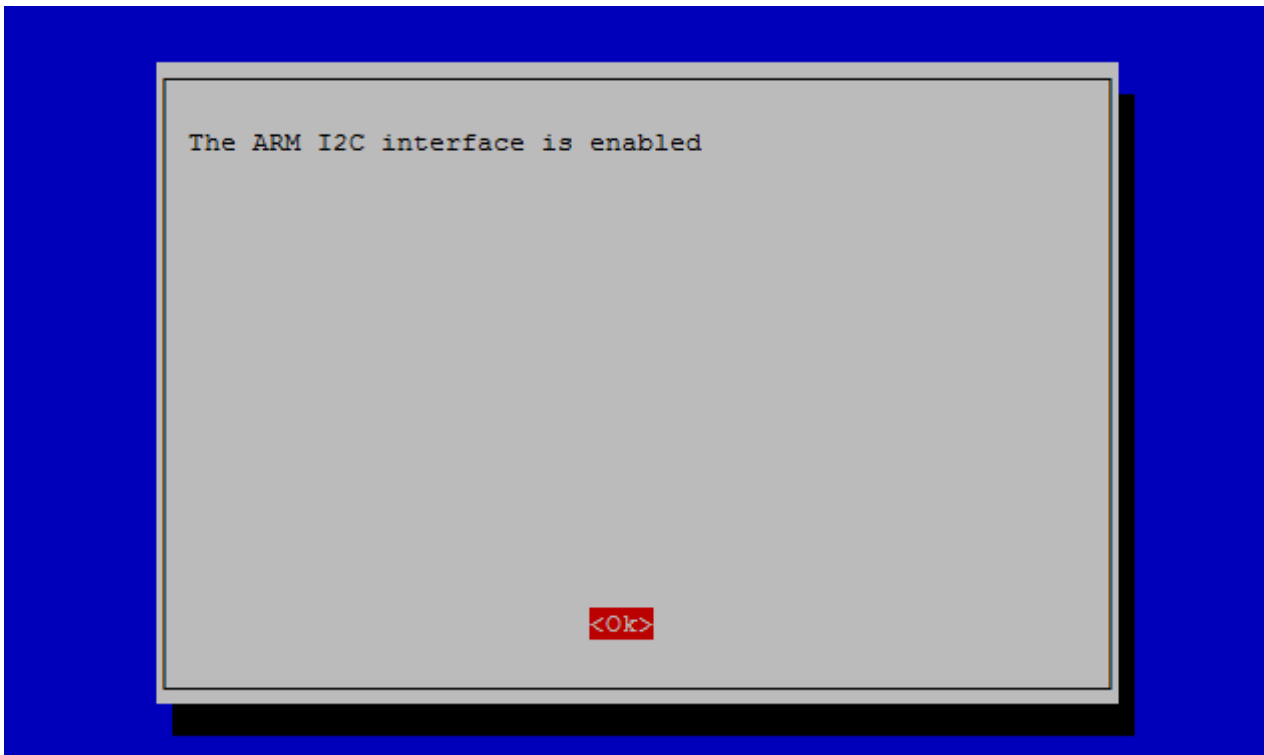
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Choose "I2C"



Choose "YES"



Hit "OK" and reboot the Raspberry Pi.

```
sudo reboot
```

Raspberry Pi sample code

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Your Atlas Scientific™ EZO™ class circuits are almost ready to work with your Raspberry Pi, we just have to run a simple test first.

Connect your EZO™ class circuit, and run the following command in terminal.

```
sudo i2cdetect -y 1
```

```

    0  1  2  3  4  5  6  7  8  9  a  b  c  d  e  f
00:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
10:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
20:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
30:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
40:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
50:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
60:  --  --  --  63  --  --  --  --  --  --  --  --  --  --  --  --
70:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --

```

I2C address list

Device	Decimal	Hex
pH	99	0x63
ORP	98	0x62
DO	97	0x61
EC	100	0x64
RTD	102	0x66
PMP	103	0x67

The program will report information about each connected I²C device. This shows that an I²C address (0x63) is in use.

Run the following commands in terminal.

```
cd ~/Raspberry-Pi-sample-code
```

```
sudo python i2c.py
```

Each Atlas Scientific™ device has a different default I²C address.

To see a list of connected I²C devices from the program, use the command

```
List_addr
```

The last step is to tell the Raspberry Pi which circuit you want to talk to. For example, if you give the command (*address, 99*), the Raspberry Pi will now send all command to the pH circuit. Only after the Raspberry Pi knows which EZO™ circuit to communicate with, can you send EZO commands. Such as, "I", "status", "R", etc...

```
ADDRESS,99
```

This will now tell the Raspberry Pi to communicate with the EZO™ pH circuit 99 (0x63)

For more details on the commands, responses and I²C addresses, please refer to the datasheets of each Atlas Scientific™ EZO™ class circuit in use.

UART Mode



UART Mode

The Raspberry Pi Foundation has failed to make a working UART on the Pi 3. Because of this no UART connected devices can run on a Raspberry Pi 3 GPIO pins.

Before we can start using the Atlas Scientific™ EZO™ class circuits with your Raspberry Pi, we have to make a small tweak to the boot command line.

Run the following command line.

```
sudo nano /boot/cmdline.txt
```

You should see something that looks a lot like this:

```

GNU nano 2.2.6                               File: /boot/cmdline.txt
dwc_otg.lpm_enable=0 console=tty1 console=serial0,115200 root=/dev/mmcblk0p2 rootfstype=ext4 elevator=deadline rootwait
                   1                   2
^G Get Help          ^O WriteOut         ^R Read File        ^Y Prev Page        ^K Cut Text         ^C Cur Pos
^X Exit             ^J Justify          ^W Where Is        ^V Next Page        ^U UnCut Text       ^T To Spell
  
```

You might see two separate commands listed for the "console".

console=tty1 **console=serial0,115200**

1 2

This can cause a conflict in the serial port.

To correct this issue, **delete** the command:

console=serial0,115200

The command line should now look like this:

```

GNU nano 2.2.6                               File: /boot/cmdline.txt
dwc_otg.lpm_enable=0 console=tty1 root=/dev/mmcblk0p2 rootfstype=ext4 elevator=deadline rootwait
^G Get Help          ^O WriteOut         ^R Read File        ^Y Prev Page        ^K Cut Text         ^C Cur Pos
^X Exit             ^J Justify          ^W Where Is        ^V Next Page        ^U UnCut Text       ^T To Spell
  
```

Press "CTRL+X", then "Y" and hit Enter to save & exit.

We need to ensure PySerial is installed for Python

```
sudo pip install pyserial
```

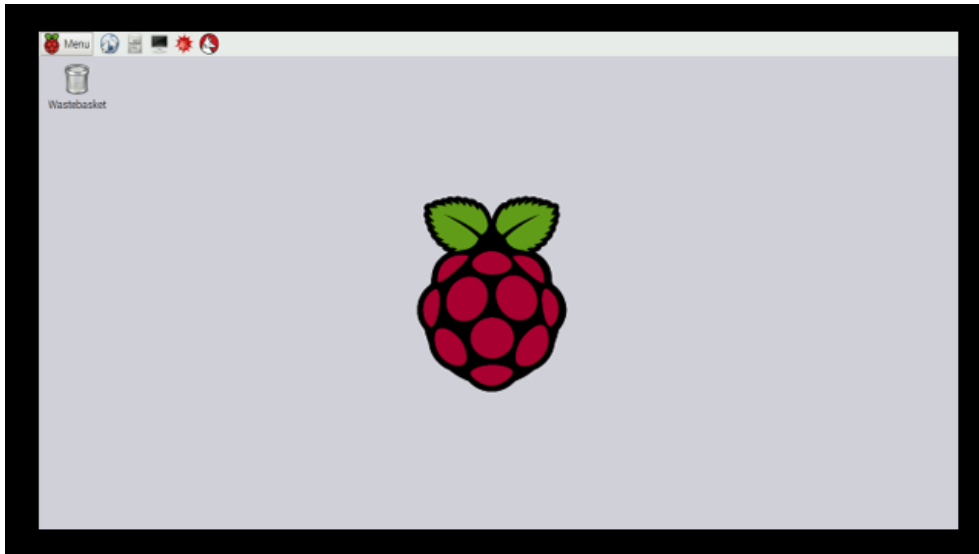
Run the following commands in terminal.

```
cd ~/Raspberry-Pi-sample-code
```

```
sudo python uart.py
```

Side note

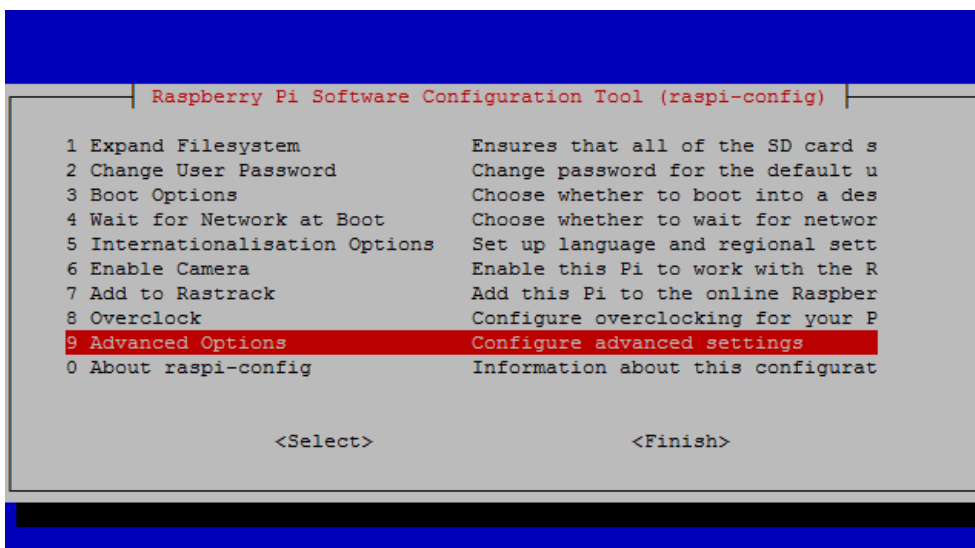
Does your Raspberry Pi have an annoying black border around the OS?



If so, here is how to remove it.

Run the following command line within the Raspberry Pi's terminal.

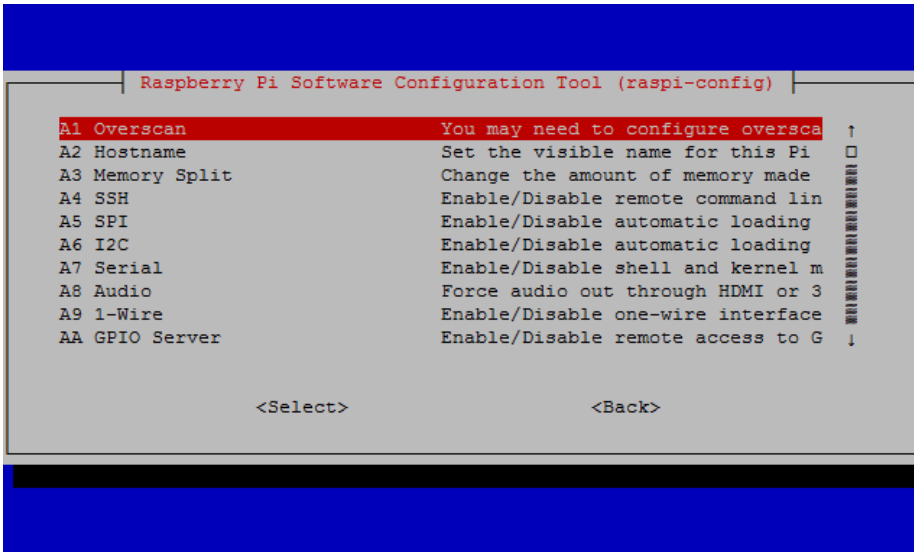
```
sudo raspi-config
```



Choose the option "Advanced Options"

Raspberry Pi sample code

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Then, choose the option "A1 Overscan"



It will ask if you would like to enable compensation for displays with overscan?
say "NO"

The black border will know be gone. Enjoy!

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